

## SECTION 2 STRUCTURE AND FUNCTION

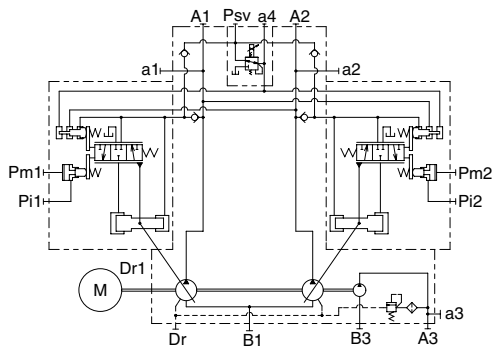
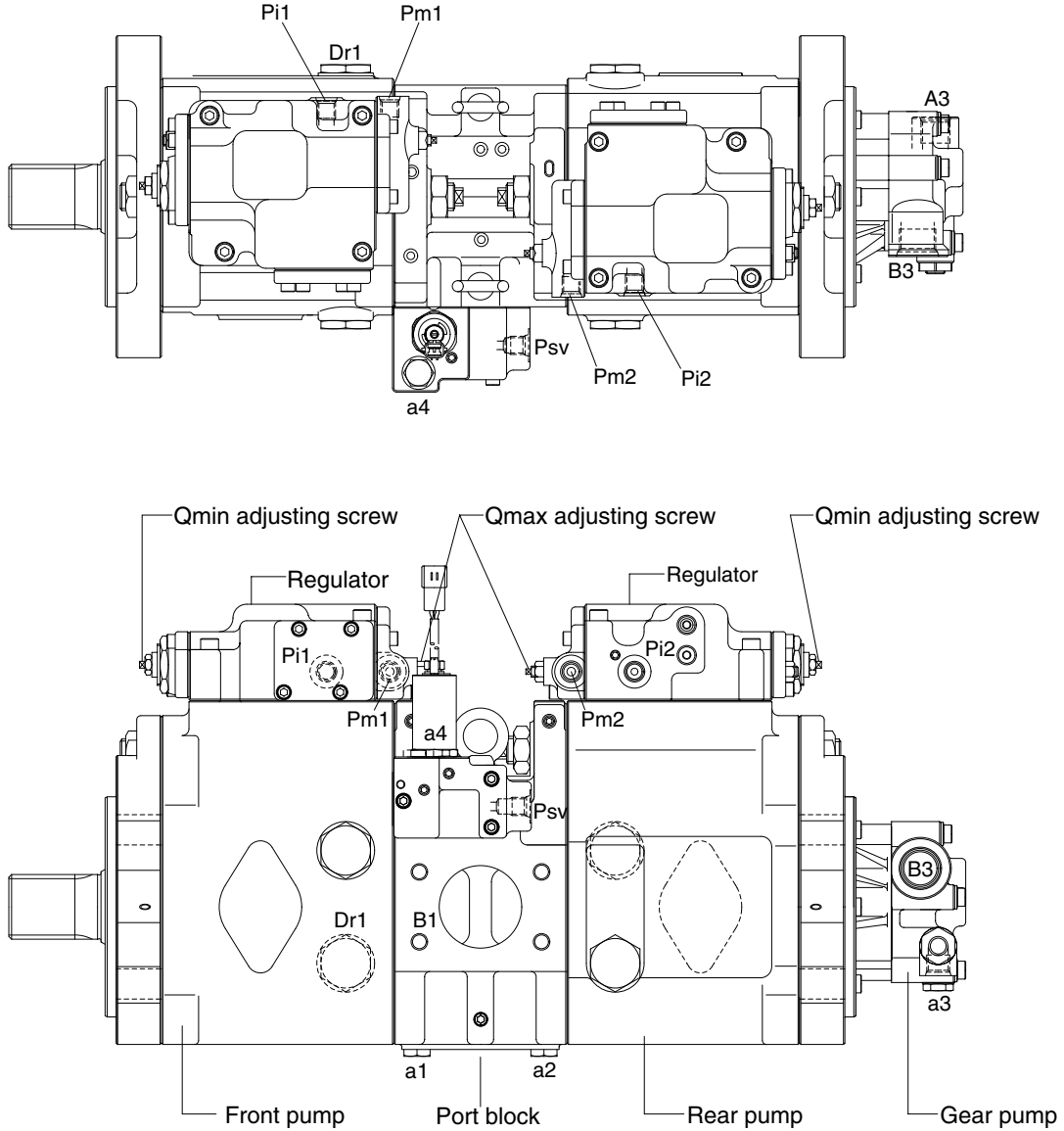
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# SECTION 2 STRUCTURE AND FUNCTION

## GROUP 1 PUMP DEVICE

### 1. STRUCTURE

The pump device consists of main pump, regulator and gear pump.

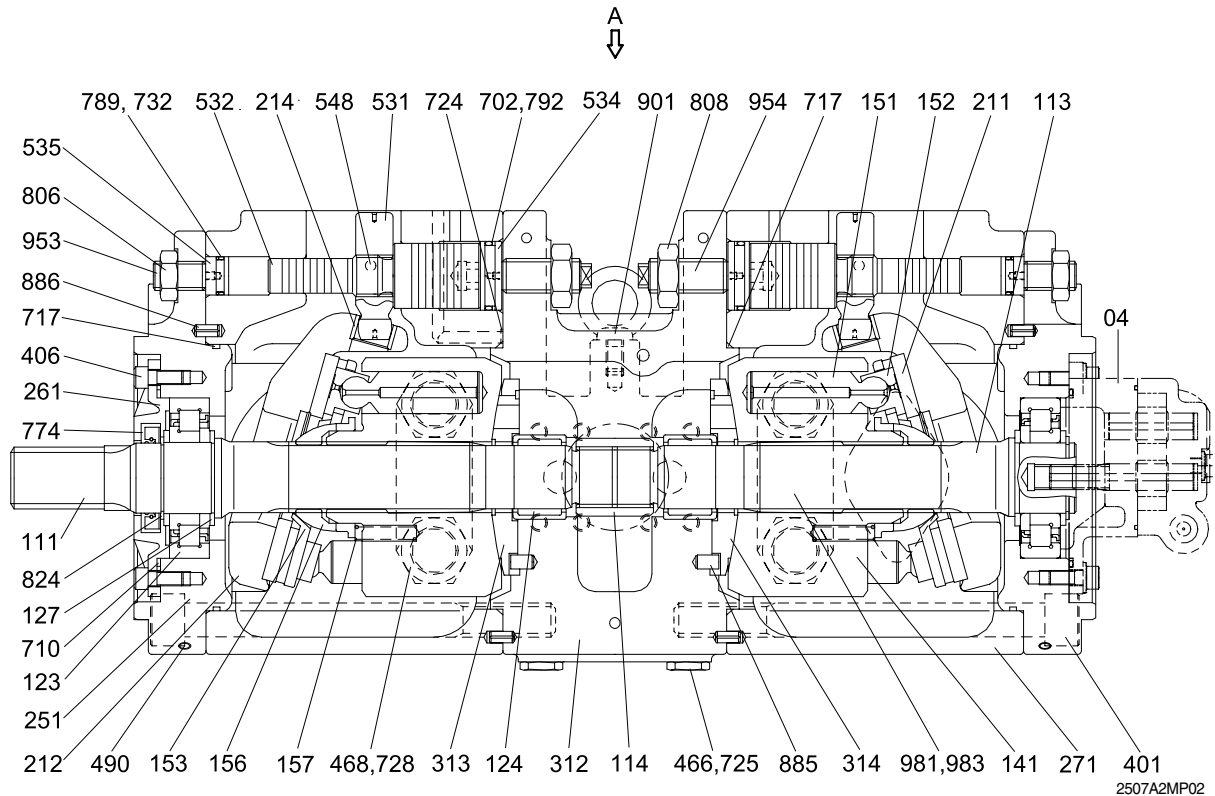


2507A2MP01

Port	Port name	Port size
A1,2	Delivery port	SAE6000psi 3/4"
B1	Suction port	SAE2500psi 2 1/2"
Dr	Drain port	PF 3/4 - 20
Pi1,i2	Pilot port	PF 1/4 - 15
Pm1,m2	Qmax cut port	PF 1/4 - 15
Psv	Servo assist port	PF 1/4 - 15
a1,2,4	Gauge port	PF 1/4 - 15
a3	Gauge port	PF 1/4 - 14
A3	Gear pump delivery port	PF 1/2 - 19
B3	Gear pump suction port	PF 3/4 - 20.5

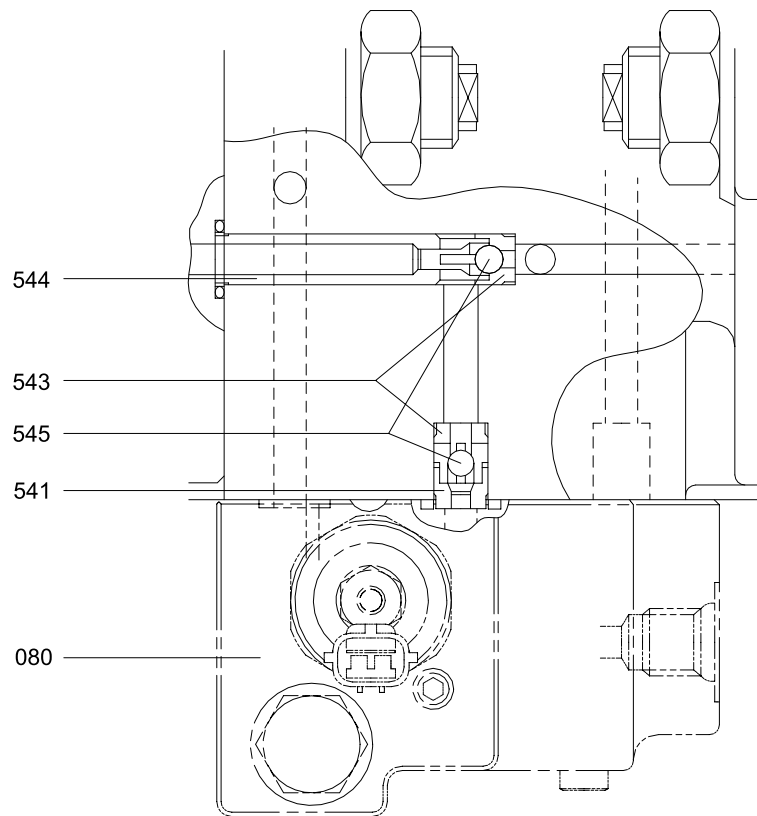
## 1) MAIN PUMP(1/2)

The main pump consists of two piston pumps(front & rear) and valve block.



04	Gear pump	271	Pump casing	724	O-ring
111	Drive shaft(F)	312	Valve block	725	O-ring
113	Drive shaft(R)	313	Valve plate(R)	728	O-ring
114	Spline coupling	314	Valve plate(L)	732	O-ring
123	Roller bearing	401	Hexagon socket bolt	774	Oil seal
124	Needle bearing	406	Hexagon socket bolt	789	Back up ring
127	Bearing spacer	466	VP plug	792	Back up ring
141	Cylinder block	468	VP plug	806	Hexagon head nut
151	Piston	490	VP plug	808	Hexagon head nut
152	Shoe	531	Tilting pin	824	Snap ring
153	Push plate	532	Servo piston	885	Pin
156	Bushing	534	Stopper(L)	886	Spring pin
157	Cylinder spring	535	Stopper(S)	901	Eye bolt
211	Shoe plate	548	Pin	953	Set screw
212	Swash plate	702	O-ring	954	Set screw
214	Bushing	710	O-ring	981	Name plate
251	Swash plate support	717	O-ring	983	Pin
261	Seal cover(F)				

## MAIN PUMP(2/2)



VIEW A

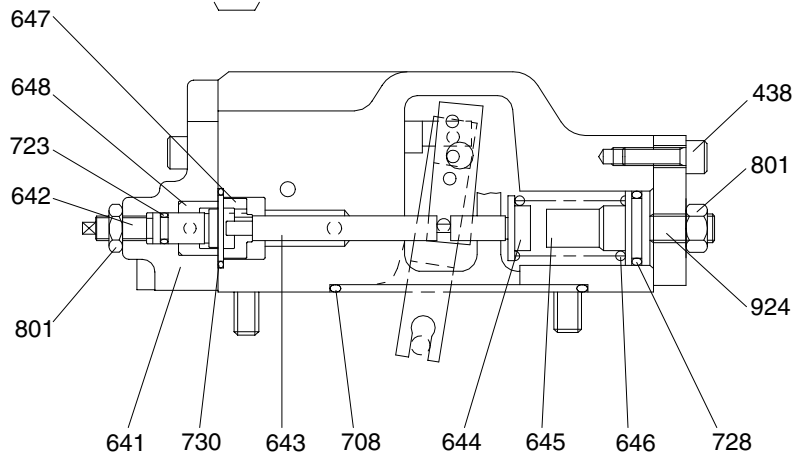
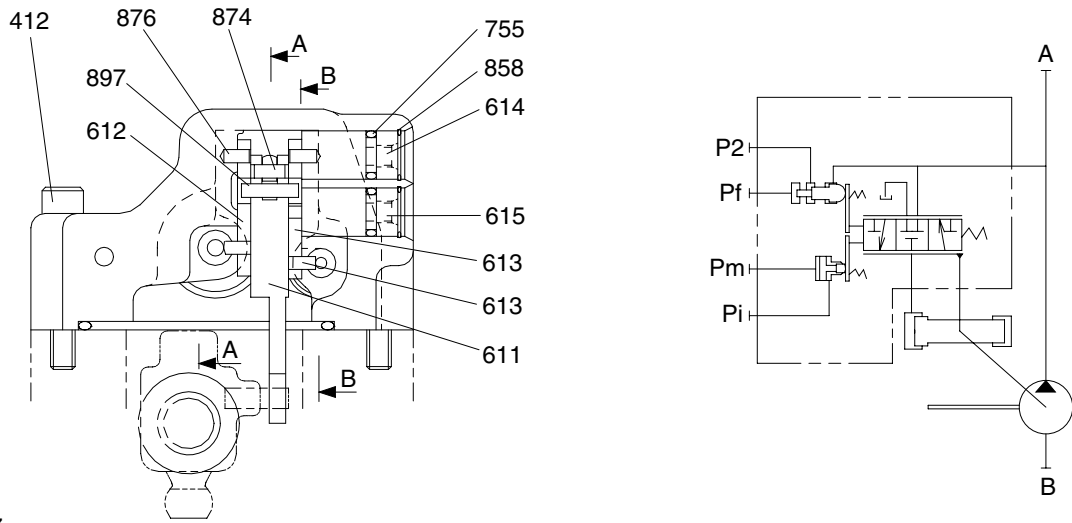
2507A2MP03

080 Proportional reducing valve  
541 Seat

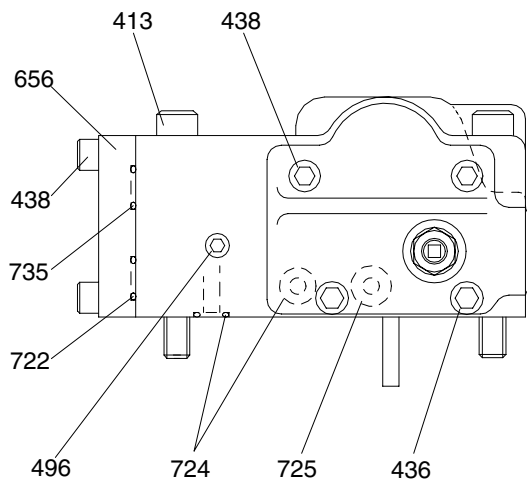
543 Stopper 1  
544 Stopper 2

545 Steel ball

## 2) REGULATOR(1/2)



SECTION B-B

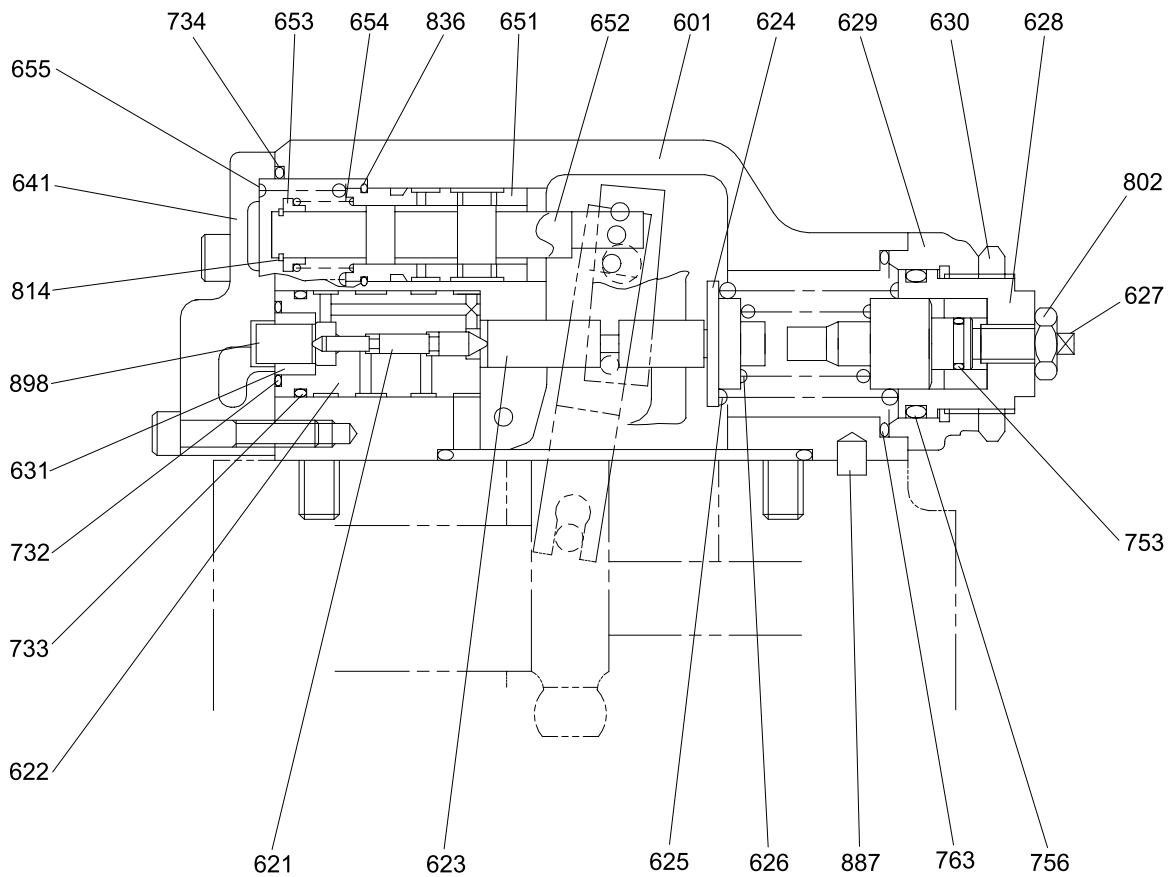


VIEW C

Port	Port name	port size
A	Delivery port	SAE 6000psi 3/4"
B	Suction port	SAE 2500psi 2 1/2"
Pi	Pilot port	PF 1/4-15
Pm	Qmax cut port	PF 1/4-15

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## REGULATOR(2/2)

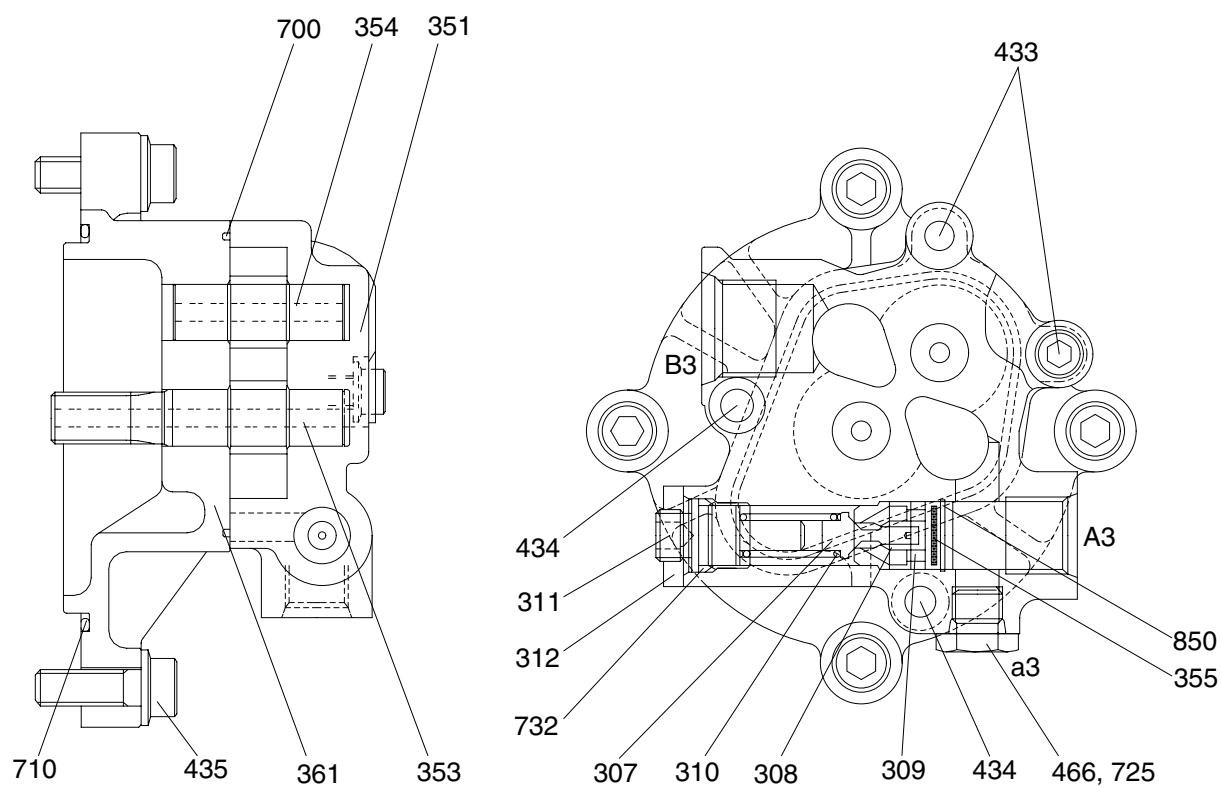


SECTION A-A

2507A2MP05

412 Hexagon socket screw	631 Sleeve, pf	730 O-ring
413 Hexagon socket screw	641 Pilot cover	732 O-ring
436 Hexagon socket screw	642 Adjust screw(QMC)	733 O-ring
438 Hexagon socket screw	643 Pilot piston	734 O-ring
496 Plug	644 Spring seat(Q)	735 O-ring
601 Casing	645 Adjust stem(Q)	753 O-ring
611 Feed back lever	646 Pilot spring	755 O-ring
612 Lever(1)	647 Stopper	756 O-ring
613 Lever(2)	648 Piston(QMC)	763 O-ring
614 Fulcrum plug	651 Sleeve	801 Nut
615 Adjust plug	652 Spool	802 Nut
621 Compensator piston	653 Spring seat	814 Snap ring
622 Piston case	654 Return spring	836 Snap ring
623 Compensator rod	655 Set spring	858 Snap ring
624 Spring seat(C)	656 Block cover	874 pin
625 Outer spring	708 O-ring	875 Pin
626 Inner spring	722 O-ring	887 Pin
627 Adjust stem(C)	723 O-ring	897 Pin
628 Adjust screw(C)	724 O-ring	898 Pin
629 Cover(C)	725 O-ring	924 Set screw
630 Lock nut	728 O-ring	

### 3) GEAR PUMP



2507A2MP06

307 Poppet  
 308 Seat  
 309 Ring  
 310 Spring  
 311 Screw  
 312 Nut  
 351 Gear case

353 Drive gear  
 354 Driven gear  
 355 Filter  
 433 Flange socket  
 434 Flange socket  
 435 Flange socket

466 Plug  
 700 Ring  
 710 O-ring  
 725 O-ring  
 732 O-ring  
 850 Snap ring

## 2. FUNCTION

### 1) MAIN PUMP

The pumps may be classified roughly into the rotary group performing a rotary motion and working as the major part of the whole pump function: the swash plate group that varies the delivery rates: and the valve cover group that changes over oil suction and discharge.

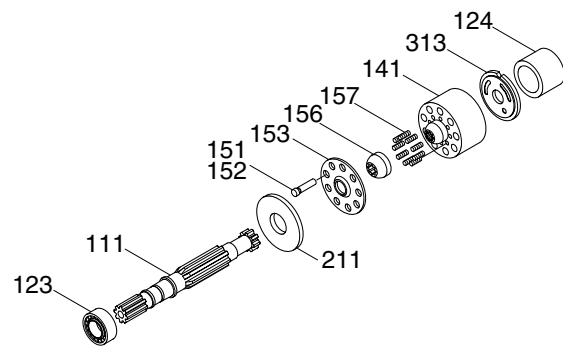
#### (1) Rotary group

The rotary group consists of drive shaft (F)(111), cylinder block(141), piston shoes(151,152), set plate(153), spherical bush(156) and cylinder spring(157).

The drive shaft is supported by bearing(123,124) at its both ends.

The shoe is caulked to the piston to form a spherical coupling. It has a pocket to relieve thrust force generated by loading pressure and to take hydraulic balance so that it slides lightly over the shoe plate(211). The sub group composed by a piston and a shoe is pressed against the shoe plate by the action of the cylinder spring via a retainer and a spherical bush.

Similarly, the cylinder block is pressed against valve plate(313) by the action of the cylinder spring.



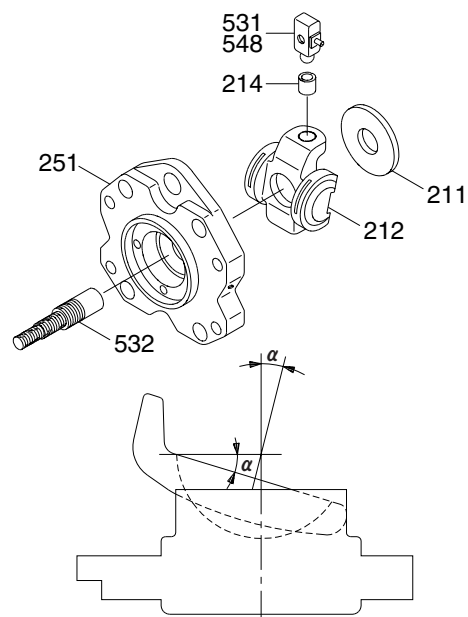
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#### (2) Swash plate group

The swash plate group consists of swash plate(212), shoe plate(211), swash plate support(251), tilting bush(214), tilting pin(531) and servo piston(532).

The swash plate is a cylindrical part formed on the opposite side of the sliding surface of the shoe and is supported by the swash support.

If the servo piston moves to the right and left as hydraulic force controlled by the regulator is admitted to hydraulic chamber located on both sides of the servo piston, the swash plate slides over the swash plate support via the spherical part of the tilting pin to change the tilting angle( $\alpha$ )



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### (3) Valve block group

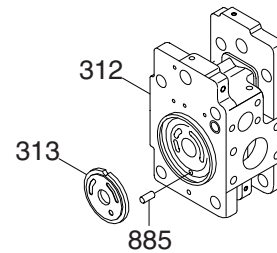
The valve block group consists of valve block(312), valve plate(313) and valve plate pin(885).

The valve plate having two melon-shaped ports is fixed to the valve block and feeds and collects oil to and from the cylinder block.

The oil changed over by the valve plate is connected to an external pipeline by way of the valve block.

Now, if the drive shaft is driven by a prime mover(electric motor, engine, etc), it rotates the cylinder block via a spline linkage at the same time. If the swash plate is tilted as in Fig(previous page) the pistons arranged in the cylinder block make a reciprocating motion with respect to the cylinder block, while they revolve with the cylinder block.

If you pay attention to a single piston, it performs a motion away from the valve plate(oil sucking process) within 180 degrees, and makes a motion towards the valve plate(or oil discharging process) in the rest of 180 degrees. When the swash plate has a tilting angle of zero, the piston makes no stroke and discharges no oil.



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## 2) REGULATOR

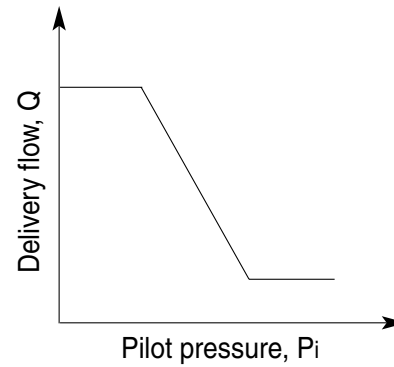
Regulator consists of the negative flow control, total horse power control and power shift control function.

### (1) Negative flow control

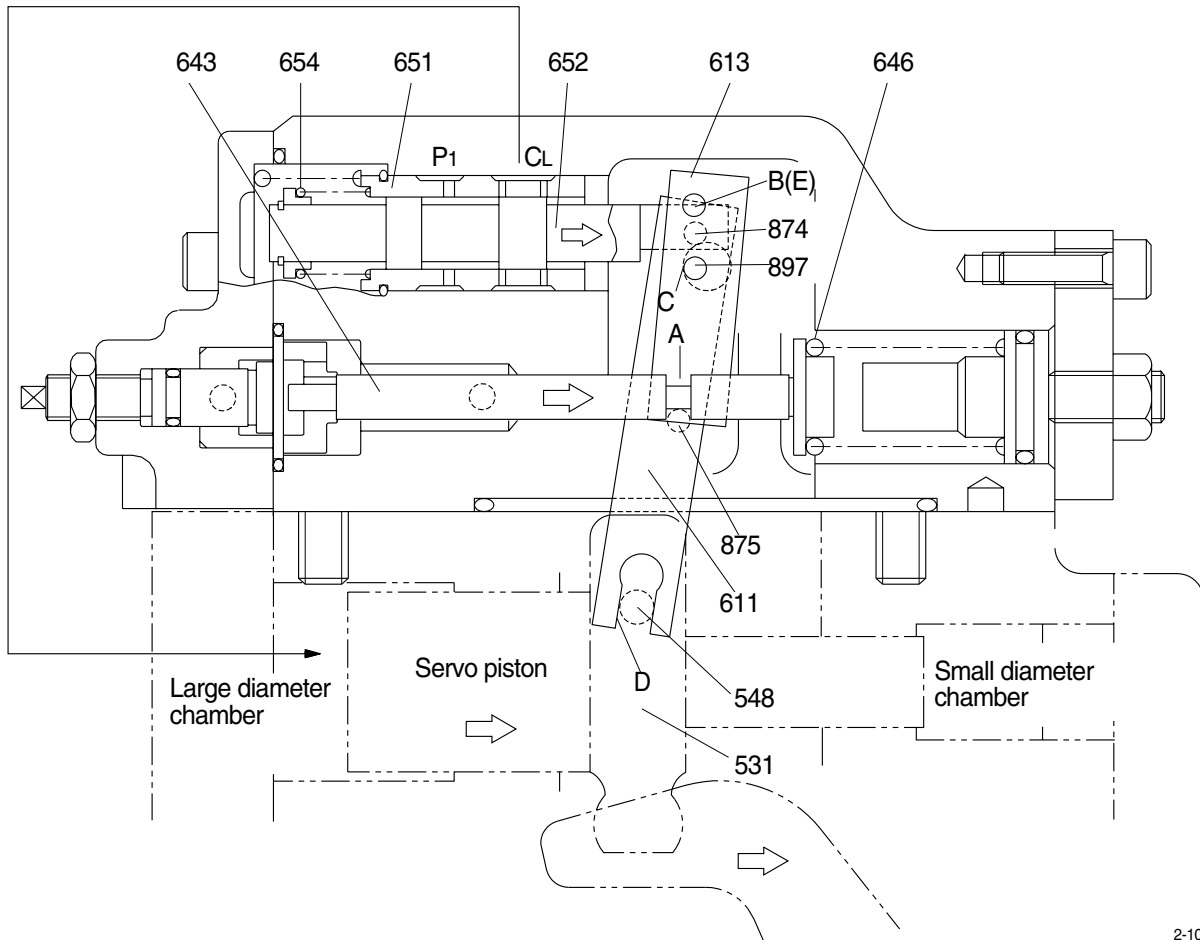
By changing the pilot pressure  $P_i$ , the pump tilting angle (delivery flow) is regulated arbitrarily, as shown in the figure.

This regulator is of the negative flow control in which the delivery flow  $Q$  decreases as the pilot pressure  $P_i$  rises.

With this mechanism, when the pilot pressure corresponding to the flow required for the work is commanded, the pump discharges the required flow only, and so it does not consume the power uselessly.



## ① Flow reducing function



2-10

As the pilot pressure  $P_i$  rises, the pilot piston(643) moves to the right to a position where the force of the pilot spring(646) balances with the hydraulic force.

The groove(A) in the pilot piston is fitted with the pin(875) that is fixed to lever 2(613). Therefore, when the pilot piston moves, lever 2 rotates around the fulcrum of point B [Fixed by the fulcrum plug(614) and pin(875)]. Since the large hole section(C) of lever 2 contains a protruding pin(897) fixed to the feedback lever(611), the pin(897) moves to the right as lever 2 rotates. Since the opposing-flat section(D) of the feedback lever is fitted with the pin(548) fixed by the tilting pin(531) that swings the swash plate, the feedback lever rotates around the fulcrum of point D, as the pin(897) moves.

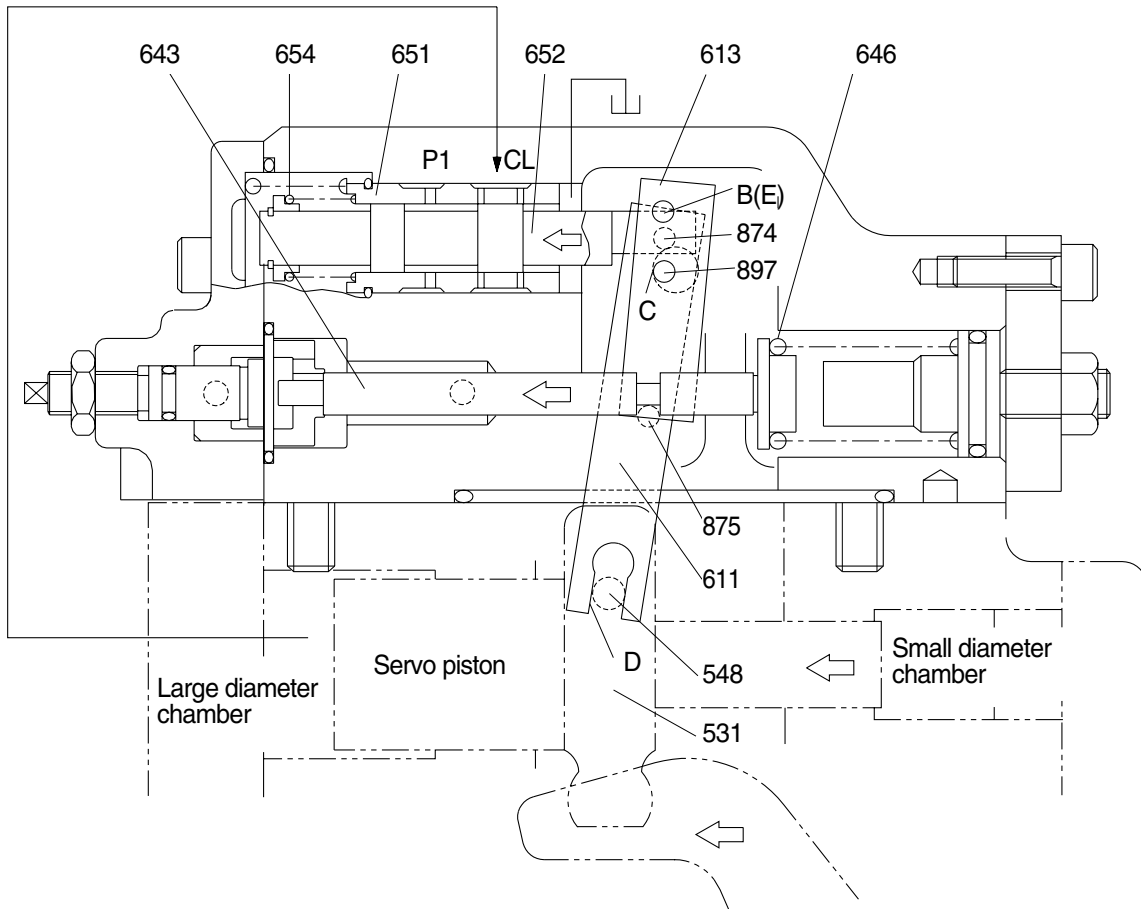
Since the feedback lever is connected with the spool(652) via the pin(874), the spool moves to the right.

The movement of the spool causes the delivery pressure  $P_1$  to connect to port CL through the spool and to be admitted to the large diameter section of the servo piston. The delivery pressure  $P_1$  that is constantly admitted to the small diameter section of the servo piston moves the servo piston to the right due to the area difference, resulting in decrease of the tilting angle.

When the servo piston moves to the right, point D also moves to the right. The spool is fitted with the return spring(654) and is tensioned to the left at all times, and so the pin(897) is pressed against the large hole section(C) of lever 2.

Therefore, as point D moves, the feedback lever rotates around the fulcrum of point C, and the spool is shifted to the left. This causes the opening between the sleeve(651) and spool(652) to close slowly, and the servo piston comes to a complete stop when it closes completely.

② Flow increasing function



2-11

As the pilot pressure  $P_i$  decreases, the pilot piston(643) moves to the left by the action of the pilot spring(646) and causes lever 2(613) to rotate around the fulcrum of point B. Since the pin(897) is pressed against the large hole section(C) of lever 2 by the action of the return spring(654) via the spool(652), pin(874), and feedback lever(611), the feedback lever rotates around the fulcrum of point D as lever 2 rotates, and shifts the spool to the left. Port CL opens a way to the tank port as the spool moves. This deprives the large diameter section of the servo piston of pressure, and shifts the servo piston to the left by the discharge pressure  $P_1$  in the small diameter section, resulting in an increase in the flow rate.

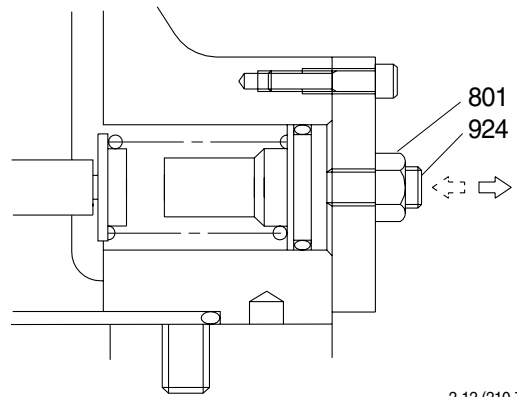
As the servo piston moves, point D also moves to the left, the feedback lever rotates around the fulcrum of point C, and the spool moves to the right till the opening between the spool and sleeve is closed.

③ **Adjustment of flow control characteristic**

The flow control characteristic can be adjusted with the adjusting screw.

Adjust it by loosening the hexagon nut (801) and by tightening(or loosening) the hexagonal socket head screw(924).

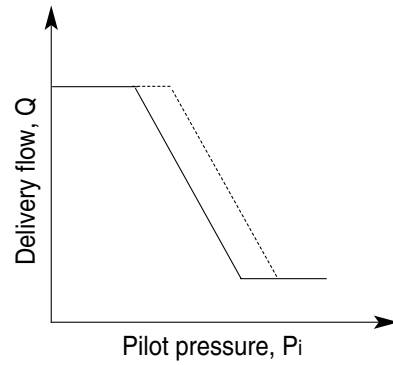
Tightening the screw shifts the control chart to the right as shown in the figure.



2-12 (210-7)

※ **Adjusting values are shown in table.**

Speed (min <sup>-1</sup> )	Adjustment of flow control characteristic		
	Tightening amount of adjusting screw(924) (Turn)	Flow control starting pressure change amount (kgf/cm <sup>2</sup> )	Flow change amount ( l /min)
1900	+1/4	+1.3	+11.7



## (2) Total horsepower control

The regulator decreases the pump tilting angle (delivery flow) automatically to limit the input torque within a certain value with a rise in the delivery pressure  $P_1$  of the self pump and the delivery pressure  $P_2$  of the companion pump.

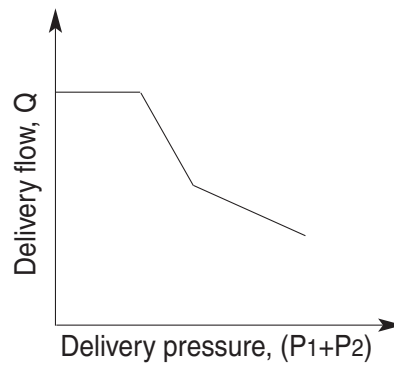
(The input horsepower is constant when the speed is constant.)

Since the regulator is of the simultaneous total horsepower type that operates by the sum of load pressures of the two pumps in the tandem double-pump system, the prime mover is automatically prevented from being overloaded, irrespective of the load condition of the two pumps, when horsepower control is under way.

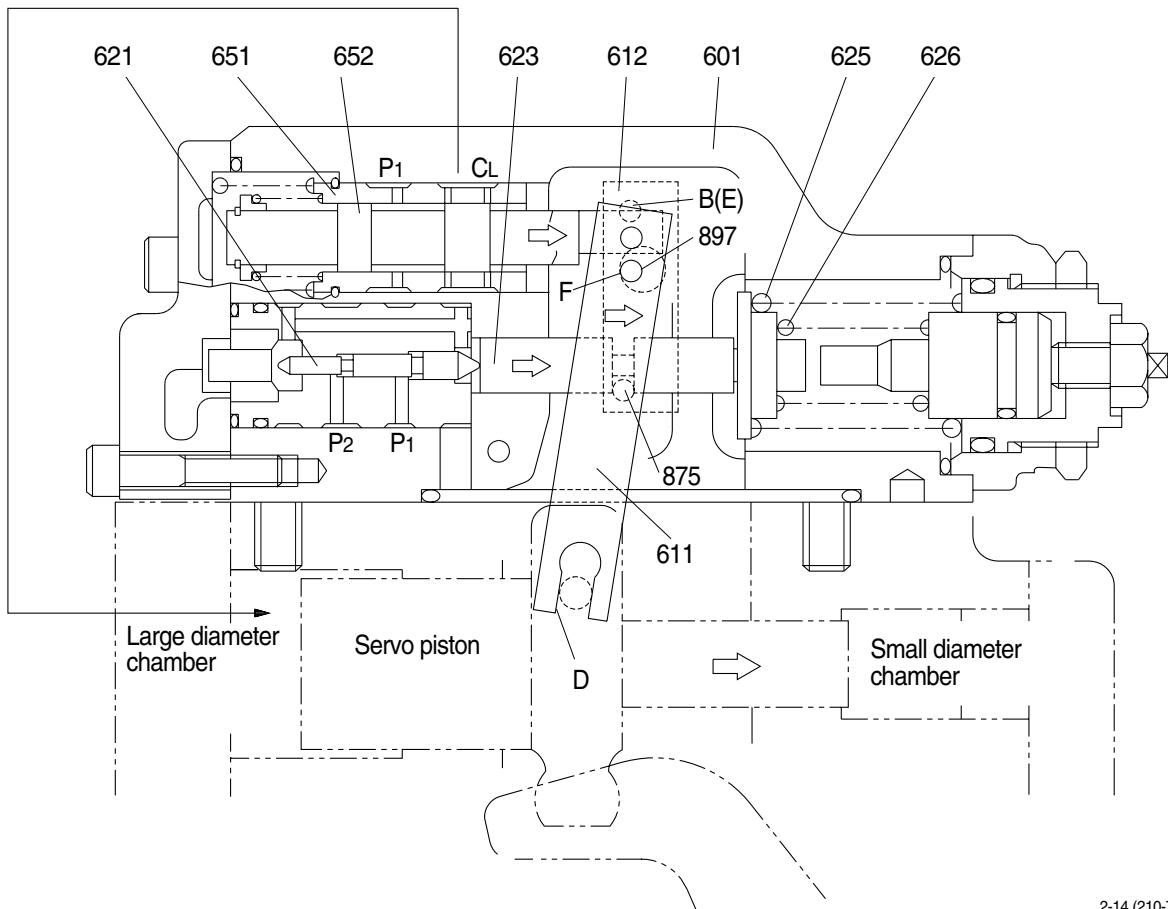
Since this regulator is of the simultaneous total horsepower type, it controls the tilting angles (displacement volumes) of the two pumps to the same value as represented by the following equation :

$$\begin{aligned} T_{in} &= P_1 \times q/2\pi + P_2 \times q/2\pi \\ &= (P_1+P_2) \times q/2\pi \end{aligned}$$

The horsepower control function is the same as the flow control function and is summarized in the following. (For detailed behaviors of respective parts, refer to the section of flow control).



## ① Overload preventive function



2-14 (210-7)

When the self pump delivery pressure P1 or the companion pump delivery pressure P2 rises, it acts on the stepped part of the compensating piston(621). It presses the compensating rod(623) to the right till the force of the outer spring(625) and inner spring(626) balances with the hydraulic force. The movement of the compensating rod is transmitted to lever 1(612) via pin(875).

Lever 1 rotates around the pin(875) (E) fixed to the casing(601).

Since the large hole section(F) of lever 1 contains a protruding pin(897) fixed to the feedback lever(611), the feedback lever rotates around the fulcrum of point D as lever 1 rotates, and then the spool(652) is shifted to the right. As the spool moves, the delivery pressure P1 is admitted to the large diameter section of the servo piston via port CL, causes the servo piston move to the right, reduces the pump delivery, flow rate, and prevents the prime mover from being overloaded.

The movement of the servo piston is transmitted to the feedback lever via point D. Then the feedback lever rotates around the fulcrum of point F and the spool is shifted to the left. The spool moves till the opening between the spool(652) and sleeve(651) is closed.



③ **Low tilting angle(low flow) command preferential function**

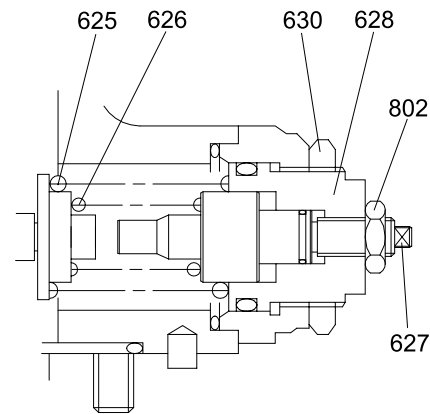
As mentioned above, flow control and horsepower control tilting angle commands are transmitted to the feedback lever and spool via the large-hole sections(C & F) of levers 1 and 2. However, since sections C and F have the pins( $\varnothing 4$ ) protruding from the large hole( $\varnothing 8$ ), only the lever lessening the tilting angle contacts the pin(897) ; the hole( $\varnothing 8$ ) in the lever of a larger tilting angle command is freed without contacting the pin(897). Such a mechanical selection method permits preference of the lower tilting angle command of the flow control and horsepower control.

④ **Adjustment of input horsepower**

Since the regulator is of total cumulative horsepower type, adjust the adjusting screws of both the front and rear pumps, when changing the horsepower set values. The pressure change values by adjustment are based on two pumps pressurized at the same time, and the values will be doubled when only one pump is loaded.

a. **Adjustment of outer spring**

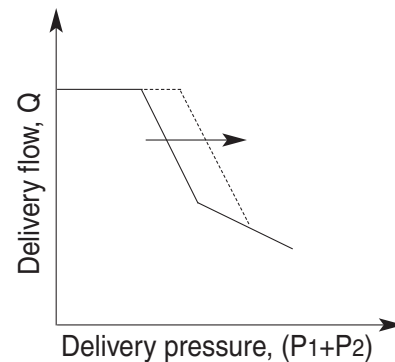
Adjust it by loosening the hexagon nut(630) and by tightening(or loosening) the adjusting screw C(628). Tightening the screw shifts the control chart to the right and increases the input horsepower as shown in the figure. Since turning the adjusting screw C by N turns changes the setting of the inner spring(626), return the adjusting stem QI(627) by  $N \times A$  turns at first.( $A=1.48$ )



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※ **Adjusting values are shown in table.**

Speed	Adjustment of outer spring		
	Tightening amount of adjusting screw(C) (628)	Compensating control starting pressure change amount	Input torque change amount
(min <sup>-1</sup> )	(Turn)	(kgf/cm <sup>2</sup> )	(kgf · m)
1900	+1/4	+15.9	+5.1



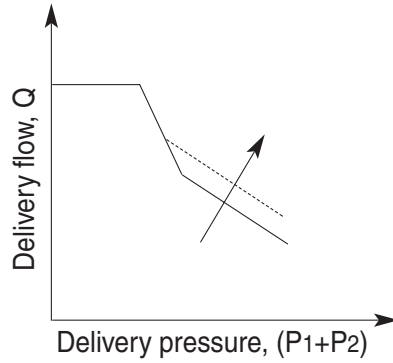
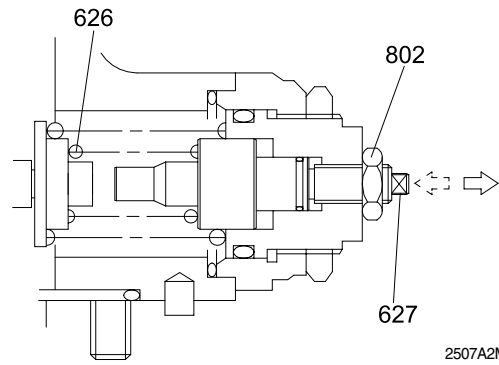
**b. Adjustment of inner spring**

Adjust it by loosening the hexagon nut (802) and by tightening(or loosening) the adjusting screw QI(627).

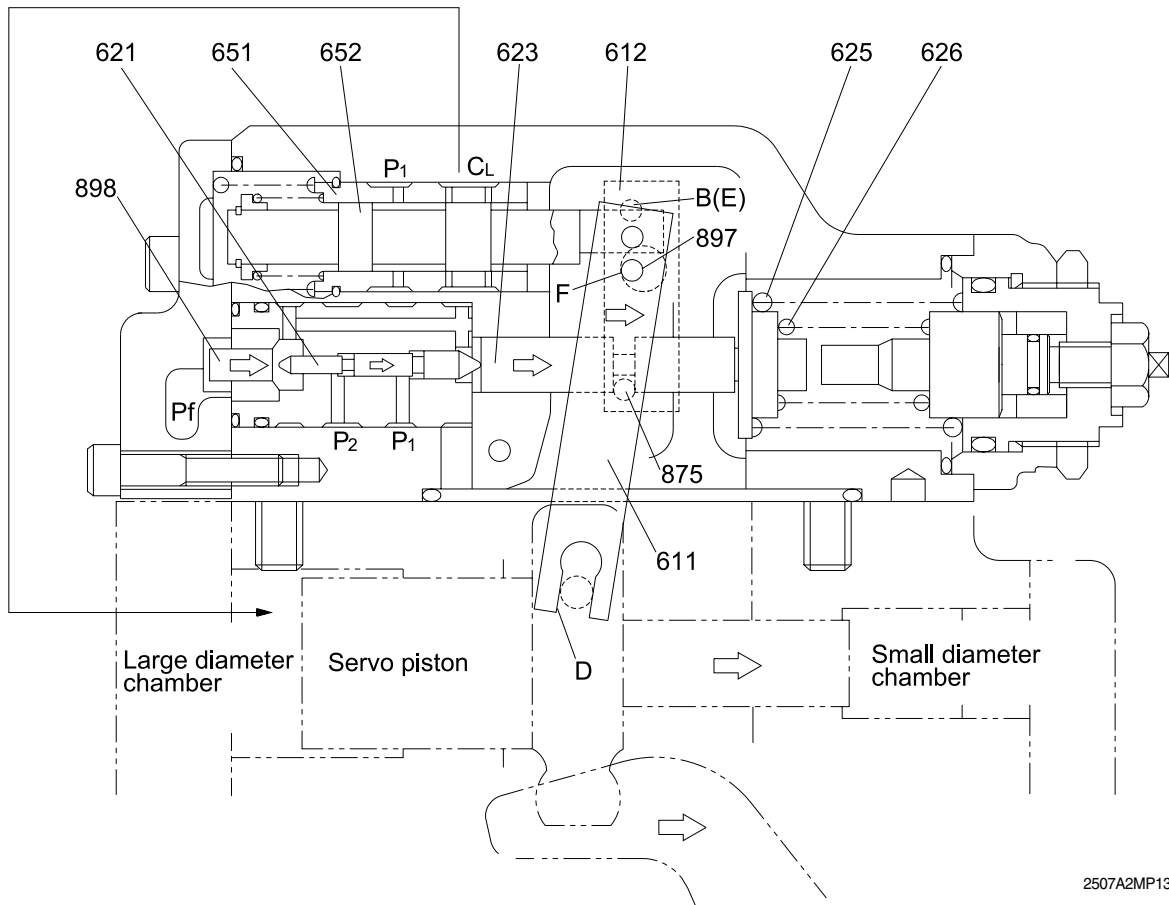
Tightening the screw increases the flow and then the input horsepower as shown in the figure.

※ **Adjusting valves are shown in table.**

Speed	Adjustment of inner spring		
	Tightening amount of adjusting screw(QI) (627)	Flow change amount	Input torque change amount
(min <sup>-1</sup> )	(Turn)	( l /min)	(kgf · m)
1900	+1/4	+10.7	+5.9



### (3) Power shift control



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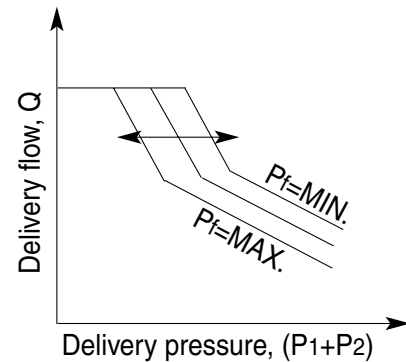
The set horsepower valve is shifted by varying the command current level of the proportional pressure reducing valve attached to the pump. Only one proportional pressure reducing valve is provided.

However, the secondary pressure  $P_f$  (power shift pressure) is admitted to the horsepower control section of each pump regulator through the pump's internal path to shift it to the same set horsepower level.

This function permits arbitrary setting of the pump output power, thereby providing the optimum power level according to the operating condition. The power shift pressure  $P_f$  controls the set horsepower of the pump to a desired level, as shown in the figure.

As the power shift pressure  $P_f$  rises, the compensating rod (623) moves to the right via the pin (898) and compensating piston (621).

This decreases the pump tilting angle and then the set horsepower in the same way as explained in the overload preventive function of the horsepower control. On the contrary, the set horsepower rises as the power shift pressure  $P_f$  falls.



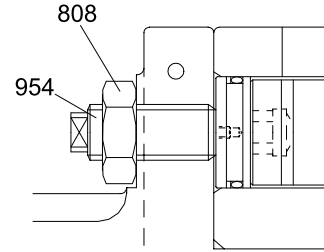
#### (4) Adjustment of maximum and minimum flows

##### ① Adjustment of maximum flow

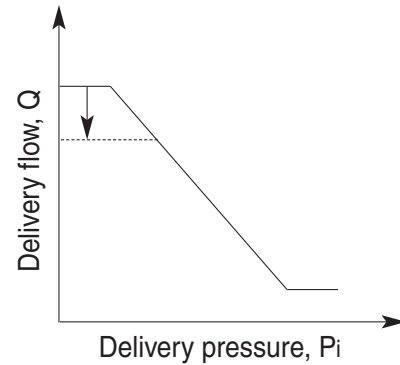
Adjust it by loosening the hexagon nut(808) and by tightening(or loosening) the set screw(954).

The maximum flow only is adjusted without changing other control characteristics.

Speed (min <sup>-1</sup> )	Adjustment of max flow	
	Tightening amount of adjusting screw (954) (Turn)	Flow change amount ( l /min)
1900	+1/4	-5.5



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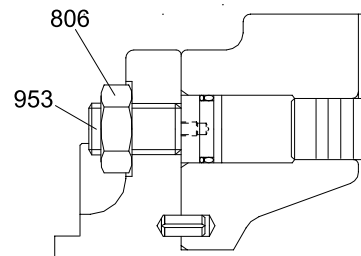


##### ② Adjustment of minimum flow

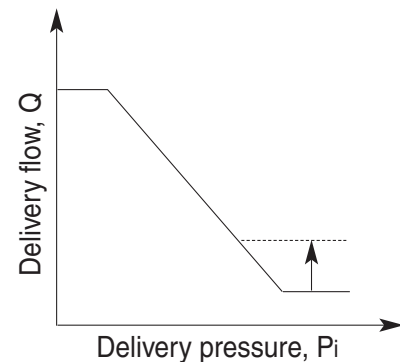
Adjust it by loosening the hexagon nut(806) and by tightening(or loosening) the hexagonal socket head set screw (953). Similarly to the adjustment of the maximum flow, other characteristics are not changed.

However, remember that, if tightened too much, the required horsepower during the maximum delivery pressure(or during relieving) may increase.

Speed (min <sup>-1</sup> )	Adjustment of min flow	
	Tightening amount of adjusting screw (953) (Turn)	Flow change amount ( l /min)
1900	+1/4	+4.4

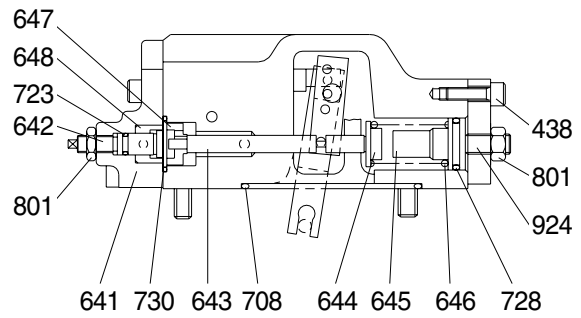


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### (5) Qmax cut control

The regulator regulates the maximum delivery flow by inputting the pilot pressure  $P_m$ . Since this is a 2-position control method, the maximum delivery flow may be switched in two steps by turning on/off the pilot pressure  $P_m$ . (The maximum control flow cannot be controlled in intermediate level.)



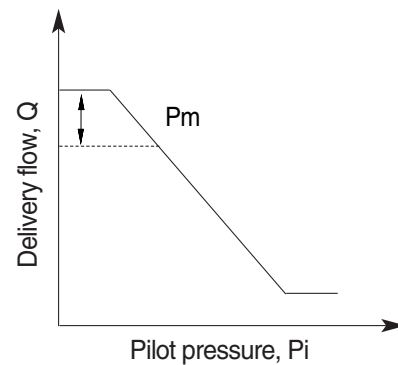
2-4

### ① Functional explanation

As shown in the figure, the pilot pressure  $P_m$  switches the maximum flow in two steps.

When the pilot pressure  $P_m$  is given, it is admitted to the lefthand side of the piston QMC(648). The piston QMC moves the stopper(647) and pilot piston(643) to the right, overcoming the force of the pilot spring(646), thereby reducing the delivery flow of the pump.

Since the adjusting screw QMC(642) is provided with a flange, the piston QMC stops upon contact with the flange, and the position of the pilot piston at this time determines the maximum flow of the pump.



### ② Adjustment of Qmax cut flow

Adjust it by loosening the hexagon nut(801) and by tightening(or loosening) the adjusting screw QMC(642).

Tightening the screw decreases the Qmax cut flow as shown in the figure.

